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# Microphysical modeling of fault friction: extension to high-velocity regime Jianye Chen<sup>\*</sup>, André R. Niemeijer, Christopher J. Spiers (Utrecht University, The Netherlands, j.chen3@uu.nl)

Recent experimental studies show that the value of friction varies over a wide range of sliding velocities (slow sliding exhibits high friction and rate-and-state behavior, and remarkable weakening occurs as velocity approaches seismic velocity). In this study, we extend a microphysically-based friction model for granular gouges (Chen and Spiers, 2016; Niemeijer and Spiers, 2007) to the highvelocity regime, by introducing additional creep mechanism(s) activated by frictional heating. The modeling results capture all of the main features and trends seen in the experiments, including both steady state and transient aspects of the observed behavior, with reasonable quantitative agreement.

### 1. Chen-Niemeijer-Spiers (CNS) Microphysical Model







# 2. Extension to high velocity regime: frictional heating actives new creep mechanism(s)



Fig. 2 Schematic model of steady-state friction as a function of log(strain rate) for granular fault.

) At low velocities, it shows velocity strengthening behavior with deformation accommodated by non-dilatant plastic creep.

2) At intermediate velocities, as the velocity increases, the friction behavior will be first controlled by dilatant granular slip that is mediated by compactional contact creep, giving rise to a velocity weakening behavior; as the velocity increases further, the frictional behavior will be controlled by GBS which is inherently rate-strengthening.

3) At high velocities, dynamic friction decreases substantially due to thermal weakening effects (e.g. thermal pressurization, flash heating, superplasticity).





Fig 3. Schematic model illustrating regimes. In the intermediate regime, GBS is accommodated by (frictional) slip, while in the highcreep accommodation velocity regime, by a (plastic) creep mechanism.

Multi-creep mechanisms:  

$$\dot{\gamma}_{pl} = \sum \dot{\gamma}_{pl}^{i}.$$

$$\dot{\gamma}_{pl} = A_{t}exp\left(-\frac{H}{RT}\right)\frac{[\tau f_{t}(\varphi)]^{n}}{d^{m}}$$

$$f_{t}(\varphi) = \left(1 - \frac{\varphi}{\varphi_{c}}\right)^{-p}$$
For carbonate gouges
$$\begin{array}{c} \text{For carbonate gouges}\\ \text{pressure solution}\\ +\\ \text{diffusion-accommodated grain}\\ \text{boundary sliding (GBS)}\\ +\\ \text{Schmid et al.(1977)}\\ \text{dislocation creep (grain size-insensitive)}\\ \text{Schmid et al.(1980)}\end{array}$$



**Future work**: (1) stability analysis; (2) earthquake cycle simulations with the extended model.

## 3. Steaty-state behavior



