

Objective: investigate incipient secondary faulting due to the propagation of a dynamic earthquake rupture on a mature fault

- * Preuss et al. (JGR, 2019) extended with:



 W_{\max} , if $W_{V_p} \ge W_{\max}$ Δx , if $W_{V_p} \leq \Delta x$

- 2.5-D model (gen. Elsasser approach; Lehner, JGR, 1981)



5 On-fault vs- off-fault plastic strain

event time |

Plastic Energy

>> Very limited plastic strain on optimally oriented fault Model RT with horizontal fault Model OOF with optimally oriented fault plastic strain $\log_{10} \varepsilon_p$ Why do we model it parallel to model boundaries?



Conclusions

- Riedel and conjugate faults generated simultaneously at tip of a pre-existing fault
- Seismic fault growth is steeper than aseismic fault growth
- Faults dominantly extend aseismically
- Structural complexity is generated seismically
- Type of off-fault deformation (distributed vs. localized) depends on bulk properties
- Amount of off-fault deformation depends on the optimality of the predefined fault



Universiteit Utrecht ETHZÜRICH

2 Seismo-Thermo-Mechanical Modeling

Van Dinther et al., (JGR, 2013b) extended to seismic time scales with adaptive time stepping and rate-and-state friction (Herrendoerfer et al., JGR, 2018) for evolving faults (Preuss et al., JGR, 2019) and novelties *













- $\tau_{\rm II}$ second invariant of stress tensor P - pressure V_p - plastic slip rate V₀ - reference slip rate
- μ_{s} static friction coefficient θ - state

CREEP

L - characteristic slip distance