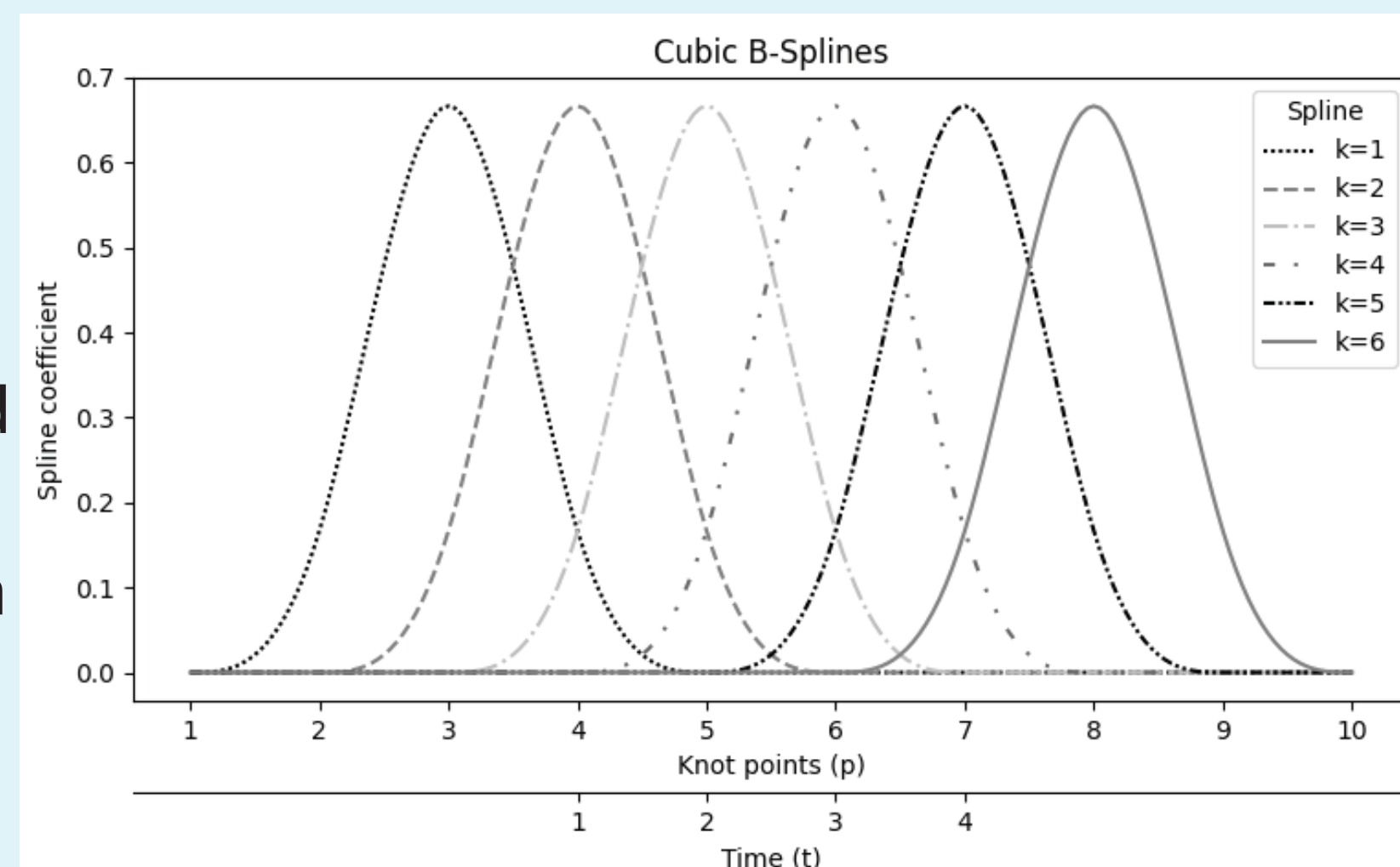


## Introduction & Motivation

- Regularized least squares models (RLS) are used in geomagnetic field modeling since the 1980's, written in **Fortran**<sup>[a,b,c,d]</sup>
- Fortran's lack of error clarity, documentation, and version control leads to maintenance challenges and compatibility issues.**<sup>[e]</sup>
- We translated RLS models into a Python version with accompanying literature overview and published on github**
- This Python version is, in terms of speed, on par with Fortran**
- RLS models require geomagnetic data and spatial and temporal smoothness constraints to invert for Gauss coefficients ( $g_1^0, g_1^1, \dots$ )
- RLS models are used for modeling historical-to-millennial scale magnetic fields<sup>[b,e,f]</sup>, snapshots thereof<sup>[g]</sup>, and reversals<sup>[h]</sup>

## Methods

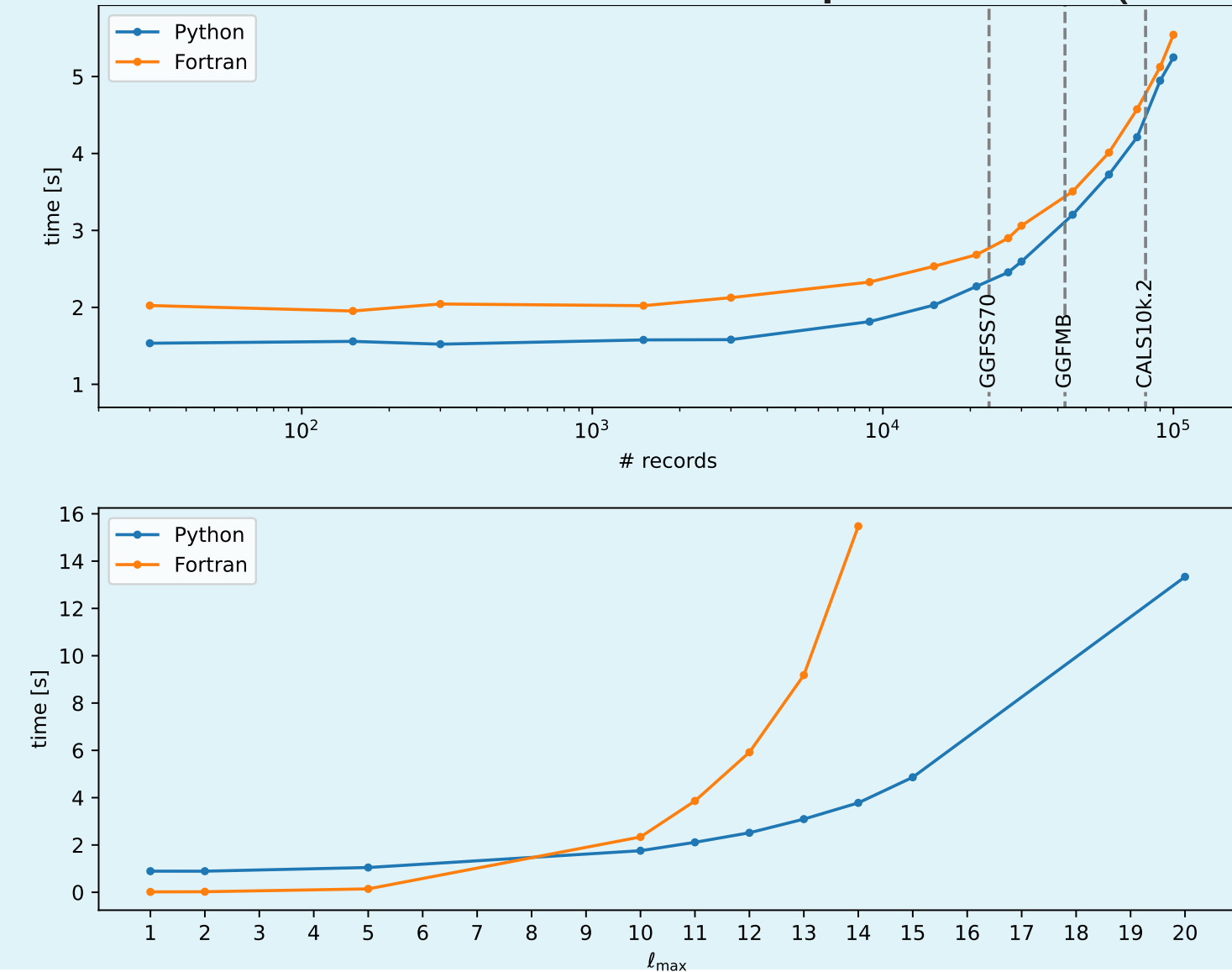
The algorithm is based on solving Laplace's equation in spherical coordinates using the source free assumption. Time-dependence is introduced with B-Splines<sup>[i,j]</sup>. The algorithm employs an iterative scheme to use non-linear data, where 8 different damping types can be imposed. However, damping parameters have lost physical basis, so model uncertainties are to be interpreted relatively. We lifted heavy computational weight with Cython and changed the structure of the algorithm to attain a further speed-up.



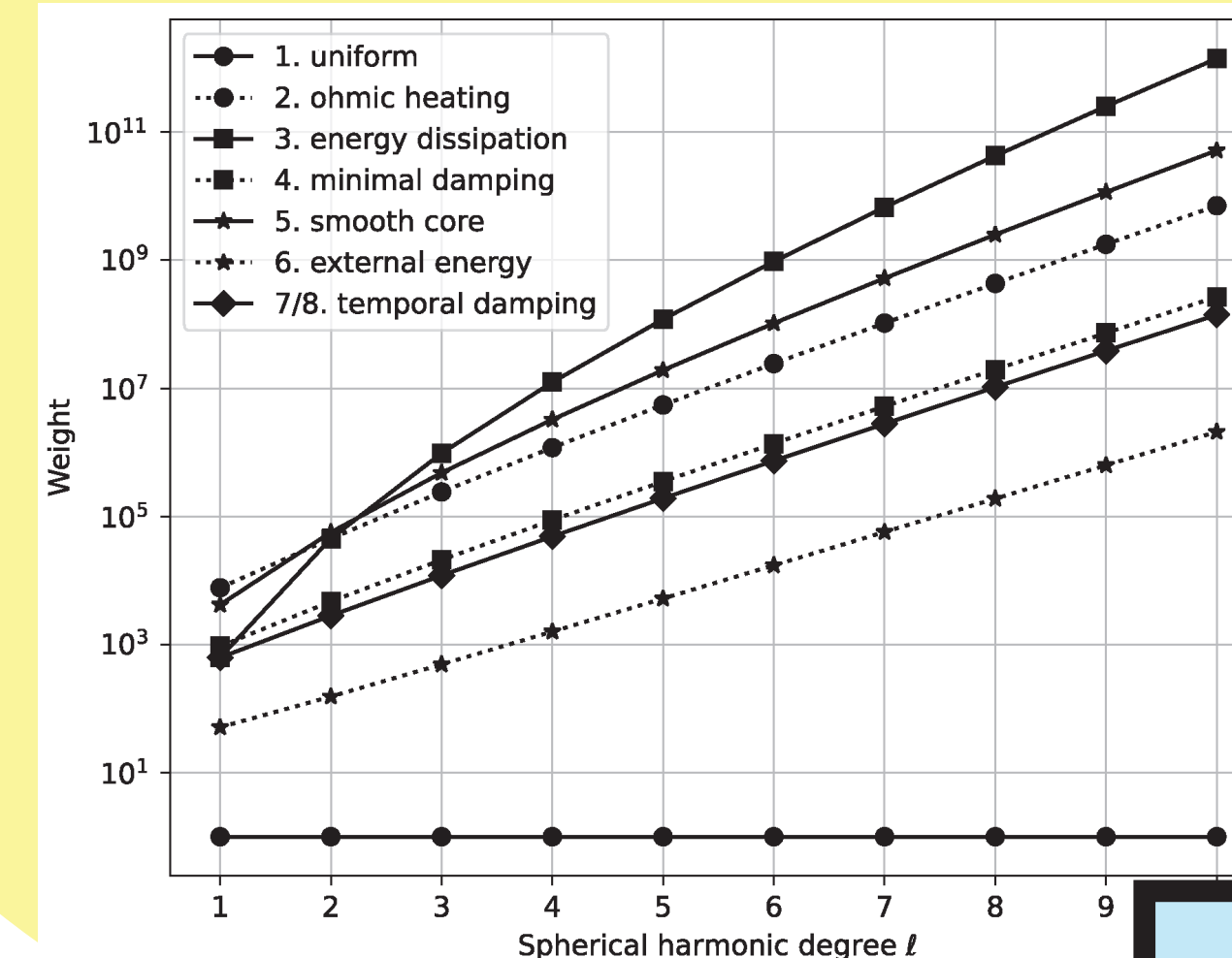
## Benchmark

To ensure consistency we compared this Python algorithm to the Fortran version. In our benchmark we employed non-linear data randomly generated using pymagglobal<sup>[m]</sup>. This benchmark shows deviations for Python less than 17 nT with a mean of 0.3 nT from the Fortran version.

> Due to different numerical precision (32-bit vs 64-bit).



**Damping**  
Constrain fast oscillations and large over swings of model through spatial and temporal damping



**Tutorials**  
included to demonstrate the capabilities of the algorithm

## Input

>>>pip install pymaginverse

**Data**  
GEOMAGIA<sup>[k,l]</sup> or own CSV dataset

**Time knots** ← **Damping parameters** → **Degree model**

## Code

```
1 import numpy as np
2 import pandas as pd
3 from pathlib import Path
4 from pymaginverse import InputData, FieldInversion
5
6 # load csv-file into InputData class
7 path = Path().absolute()
8 dataset = pd.read_csv(path / 'example_data.csv', index_col=0)
9 inputdata = InputData(dataset)
10
11 ##### start geomagnetic field inversion #####
12 # set time array and maximum spherical degree
13 test_inv = FieldInversion(t_min=-2000, t_max=1990, t_step=10, maxdegree=10)
14 # load data-class and set damping types: Ohmic heating and minimum acceleration
15 test_inv.prepare_inversion(inputdata, spat_type='ohmic_heating',
16                             temp_type='min_acc')
17 # set starting model, should have 120 elements
18 x0 = np.zeros(test_inv._nr_coeffs)
19 x0[0] = -30000
20 # run inversion by setting start model, damp factors, and max # iterations
21 test_inv.run_inversion(x0, spat_damp=1.0e-13, temp_damp=1.0e-3, max_iter=5)
22 # save gauss coefficients results
23 test_inv.save_coefficients(path / 'output', file_name='example')
```

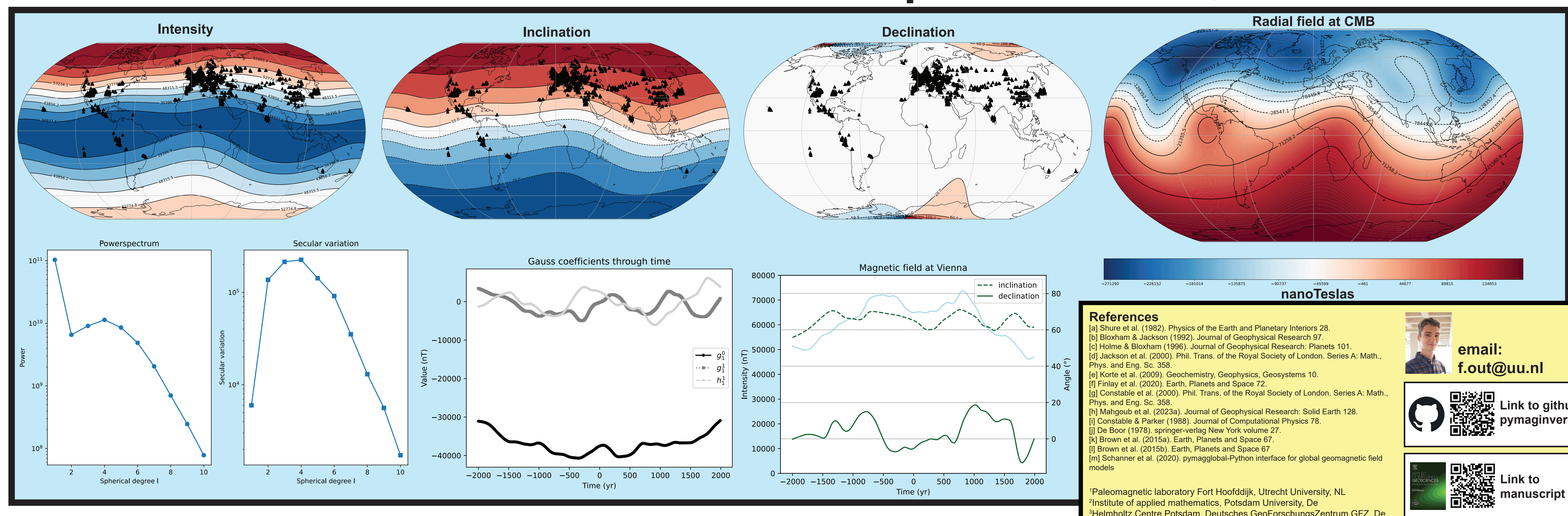
**LOAD DATA**

**INITIATE CLASS**

**RUN MODEL**

Save results in Fortran, pymagglobal<sup>[m]</sup>, or CSV-format

## Output



**References**

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 [j] De Boer (1978). springer-verlag New York volume 27.  
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 [m] Schanner et al. (2020). pymagglobal-Python interface for global geomagnetic field models

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**Link to github**  
pymaginverse

**Link to manuscript**